

# Parametric vs Nonparametric Models

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- *Parametric models* assume some **finite set of parameters**  $\theta$ . Given the parameters, future predictions,  $x$ , are independent of the observed data,  $\mathcal{D}$ :

$$P(x|\theta, \mathcal{D}) = P(x|\theta)$$

therefore  $\theta$  capture everything there is to know about the data.

- So the complexity of the model is bounded even if the amount of data is unbounded. This makes them not very flexible.

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- *Non-parametric models* assume that the data distribution cannot be defined in terms of such a finite set of parameters. But they can often be defined by assuming an **infinite dimensional**  $\theta$ . Usually we think of  $\theta$  as a **function**.
  - The amount of information that  $\theta$  can capture about the data  $\mathcal{D}$  can grow as the amount of data grows. This makes them more flexible.
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# Bayesian nonparametrics

*A simple framework for modelling complex data.*

*Nonparametric models can be viewed as having infinitely many parameters*

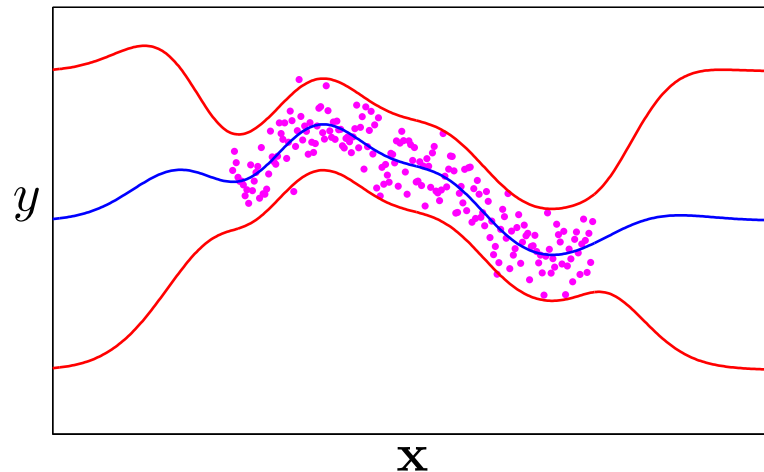
Examples of non-parametric models:

Parametric	Non-parametric	Application
polynomial regression	Gaussian processes	function approx.
logistic regression	Gaussian process classifiers	classification
mixture models, k-means	Dirichlet process mixtures	clustering
hidden Markov models	infinite HMMs	time series
factor analysis / pPCA / PMF	infinite latent factor models	feature discovery
...		

# Nonlinear regression and Gaussian processes

Consider the problem of **nonlinear regression**:

You want to learn a **function  $f$**  with **error bars** from data  $\mathcal{D} = \{\mathbf{X}, \mathbf{y}\}$



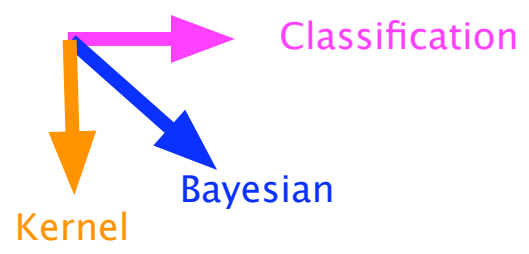
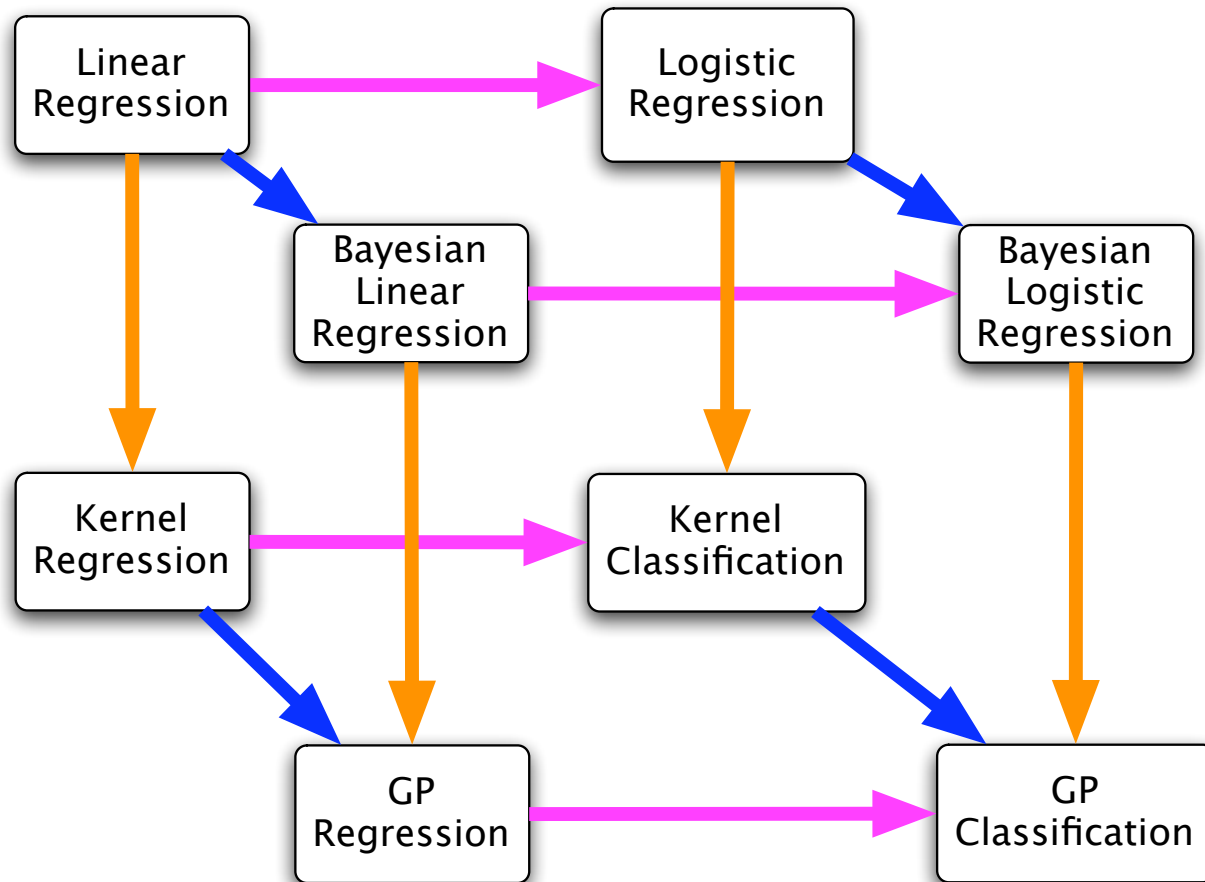
A **Gaussian process** defines a distribution over functions  $p(f)$  which can be used for Bayesian regression:

$$p(f|\mathcal{D}) = \frac{p(f)p(\mathcal{D}|f)}{p(\mathcal{D})}$$

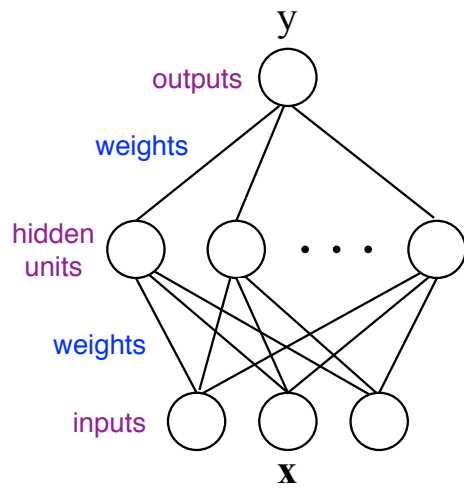
Let  $\mathbf{f} = (f(x_1), f(x_2), \dots, f(x_n))$  be an  $n$ -dimensional vector of function values evaluated at  $n$  points  $x_i \in \mathcal{X}$ . Note,  $\mathbf{f}$  is a random variable.

**Definition:**  $p(f)$  is a **Gaussian process** if for *any* finite subset  $\{x_1, \dots, x_n\} \subset \mathcal{X}$ , the marginal distribution over that subset  $p(\mathbf{f})$  is multivariate Gaussian.

# A picture



# Neural networks and Gaussian processes



## Bayesian neural network

Data:  $\mathcal{D} = \{(\mathbf{x}^{(n)}, y^{(n)})\}_{n=1}^N = (X, \mathbf{y})$

Parameters  $\boldsymbol{\theta}$  are the weights of the neural net

parameter prior

$$p(\boldsymbol{\theta}|\boldsymbol{\alpha})$$

parameter posterior

$$p(\boldsymbol{\theta}|\boldsymbol{\alpha}, \mathcal{D}) \propto p(\mathbf{y}|X, \boldsymbol{\theta})p(\boldsymbol{\theta}|\boldsymbol{\alpha})$$

prediction

$$p(y'|\mathcal{D}, \mathbf{x}', \boldsymbol{\alpha}) = \int p(y'|\mathbf{x}', \boldsymbol{\theta})p(\boldsymbol{\theta}|\mathcal{D}, \boldsymbol{\alpha}) d\boldsymbol{\theta}$$

A **Gaussian process** models functions  $y = f(\mathbf{x})$

A multilayer perceptron (neural network) with infinitely many hidden units and Gaussian priors on the weights  $\rightarrow$  a GP (Neal, 1996)

See also recent work on Deep Gaussian Processes (Damianou and Lawrence, 2013)

